Latent Dirichlet Allocation

Computational Linguistics

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Today

- Today's lecture is about a method called *Latent Dirichlet Allocation (LDA)*.
- We care about it for two reasons:
 - It's an unsupervised method for identifying *topics* and words that are representative of them.
 - It's a showcase for a family of statistical models called *Bayesian models* which have many uses in CL.

Let's start simple

- You and I are playing a coin-tossing game.
 I see you throw 63x H, 37x T.
 Should I believe that the coin is fair?
- Our model of the coin has one parameter, p = P(H).
- Maximum-likelihood estimate: p = 0.63, i.e. not fair.
- But what about
 - my uncertainty about p?
 - my prior beliefs about the fairness of the coin?

Bayesian Models

- ML estimation and similar methods deliver *point estimates:* a single value for each parameter that optimizes some criterion.
 - Likelihood: P(observations | parameters)
- Bayesian models: estimate a *probability distribution* P(parameters | observations) over parameters.
 - uncertainty about parameter values is reflected at all times in the pd

P(parameters | observations) ~ P(observations | parameters) * P(parameters) posterior likelihood prior

The Dirichlet distribution

- Take the parameter p itself as the value of a random variable.
 - need a probability distribution over real numbers;
 more specifically, over tuples of numbers that sum to one
- We use the *Dirichlet distribution*.

$$p_{1}, ..., p_{K} \sim \text{Dir}(\alpha_{1}, ..., \alpha_{K}) \text{ means:}$$

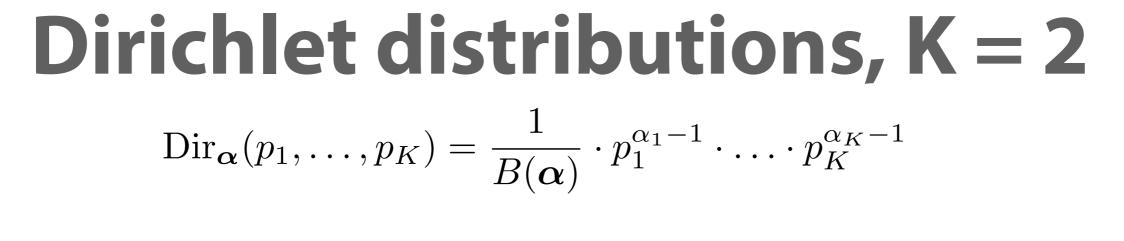
$$\text{Dir}_{\alpha}(p_{1}, ..., p_{K}) = \frac{1}{B(\alpha)} \cdot p_{1}^{\alpha_{1}-1} \cdot ... \cdot p_{K}^{\alpha_{K}-1}$$

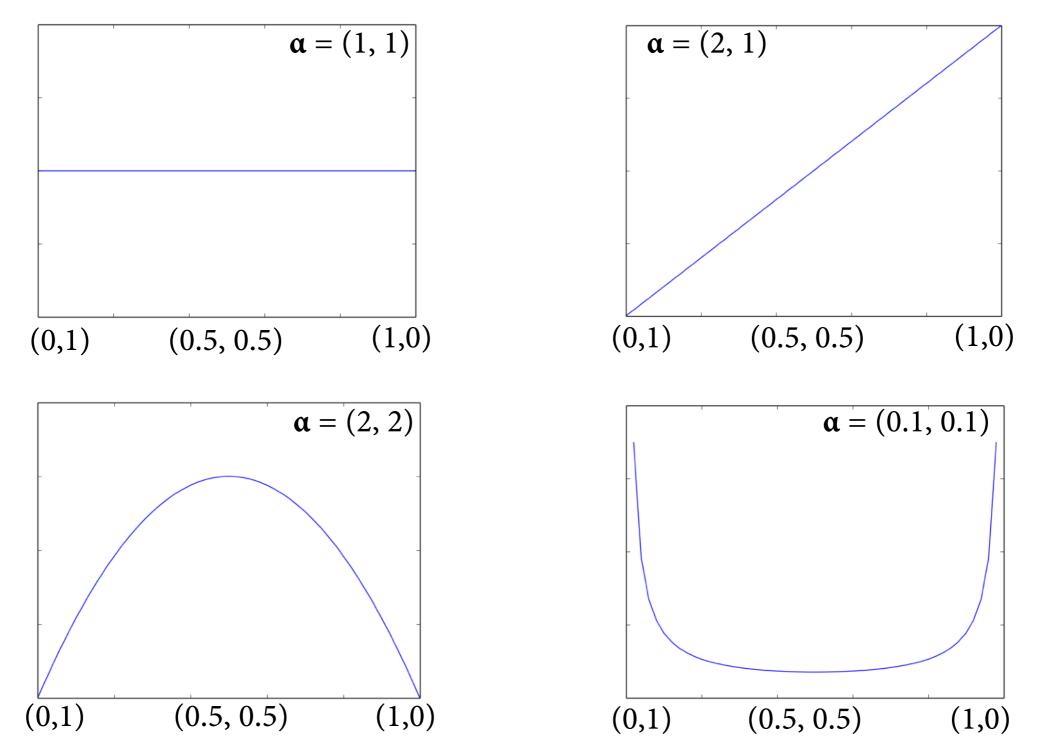
$$\text{Dir only defined if}$$

$$\text{the } p_{i} \text{ sum to } 1 \qquad \text{this is the beta function}$$

$$(\text{needed to normalize to } 1) \qquad \text{are called}$$

$$hyperparameters$$





Bayesian parameter estimation

- We are interested in pd P(M) over our model M = (p). This model is very simple; will make more complex later.
- Before we make any observations, we have a *prior distribution:* $P(M) = Dir_{\alpha,\alpha}(p, 1-p)$
- We can then *update* this to a *posterior distribution* based on observed data:

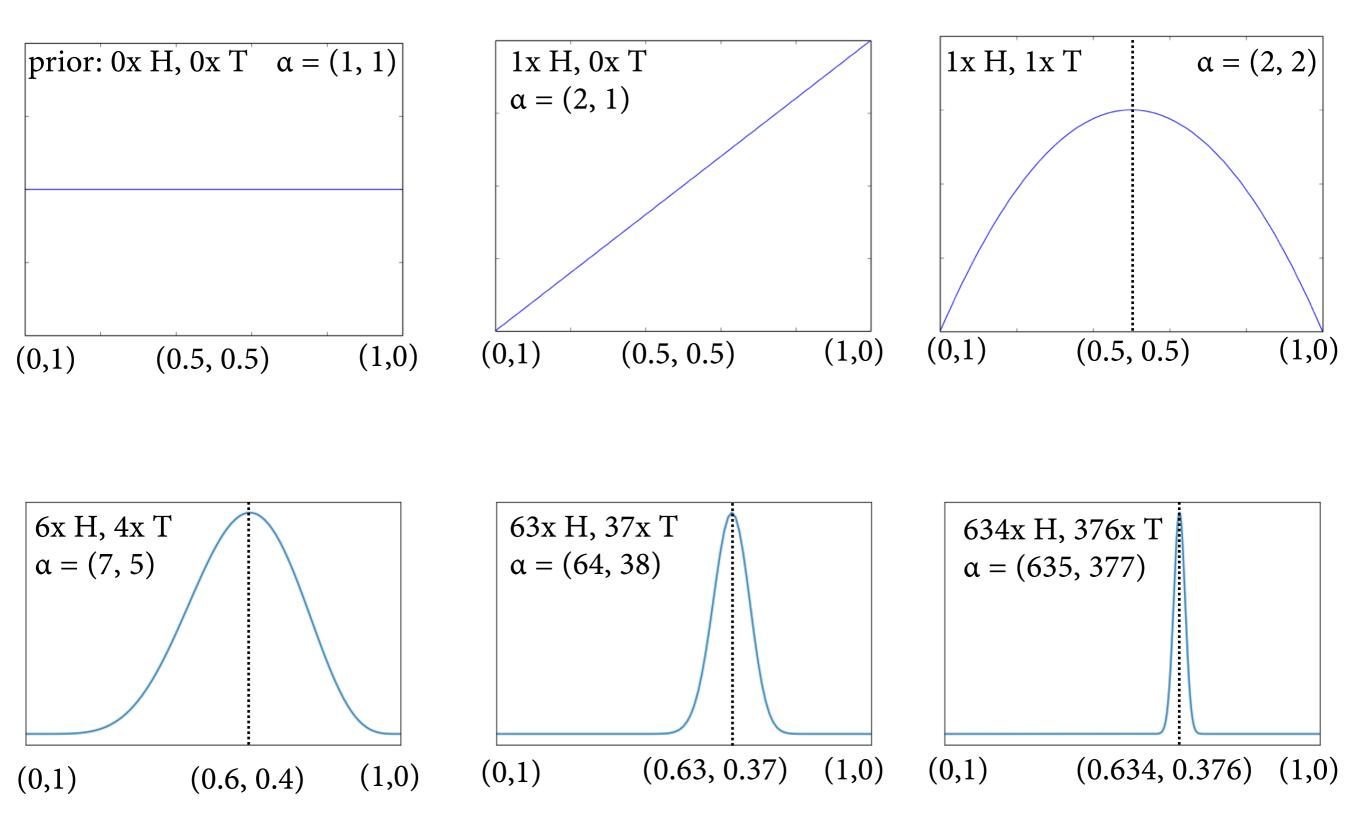
$$P(M \mid D) = \frac{P(D \mid M) \cdot P(M)}{P(D)} \propto P(D \mid M) \cdot P(M)$$
posterior likelihood prior

Calculating posteriors

prior:	$P(p) = \text{Dir}_{\alpha,\alpha}(p, 1-p) \propto p^{\alpha-1} \cdot (1-p)^{\alpha-1}$
likelihood:	$P(i \times \mathbf{H}, k \times \mathbf{T} \mid p) = p^i \cdot (1-p)^k$
posterior:	$P(p \mid i \times \mathbf{H}, k \times \mathbf{T}) \propto P(i \times \mathbf{H}, k \times \mathbf{T} \mid p) \cdot P(p)$ $\propto p^{i} \cdot (1-p)^{k} \cdot p^{\alpha-1} \cdot (1-p)^{\alpha-1}$ $= p^{i+\alpha-1} \cdot (1-p)^{k+\alpha-1}$

More precisely, we have: $P(p \mid i \times H, k \times T) = \text{Dir}_{\alpha+i,\alpha+k}(p, 1-p)$

Informed posteriors

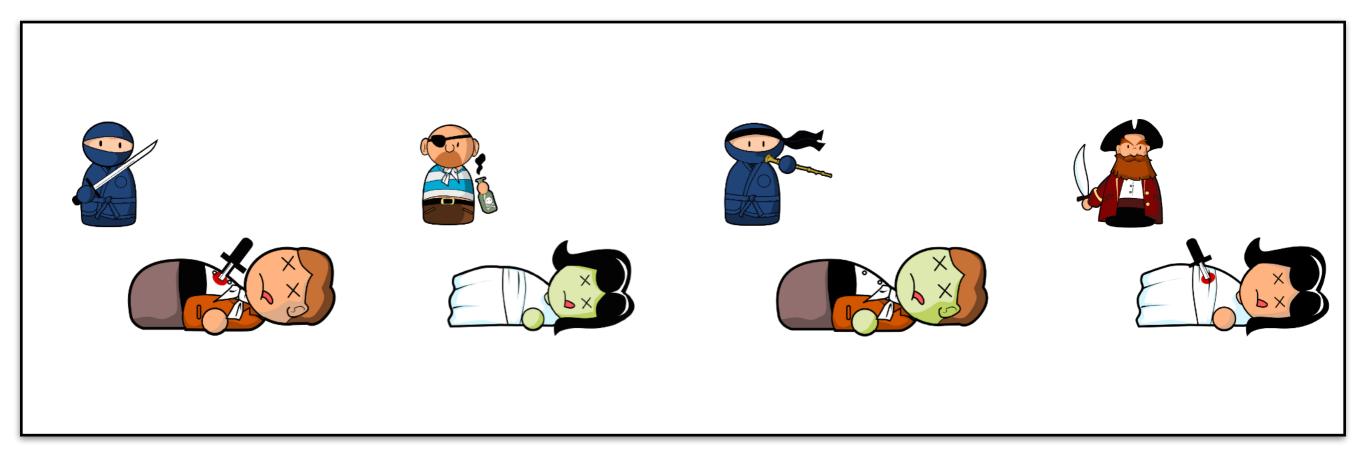


Conjugate distributions

- Crucially, P(M) and P(M | D) have the same shape (product of Dirichlets). This is because Dirichlet and Categorical are *conjugate distributions*.
 - because K = 2 for the coin, we really only used the Beta (not Dirichlet) and Bernoulli (not Categorical) distributions
- This is makes the math very convenient.
- The hyperparameters of the Dirichlets are updated by adding the observed counts to the hp. of the priors.
 - priors thus perform smoothing in a very principled way

The next step

Say you come across some people who have been stabbed or poisoned. You know that each of them was killed by a pirate or a ninja. You can tell how each person died, but not by whom they were killed.



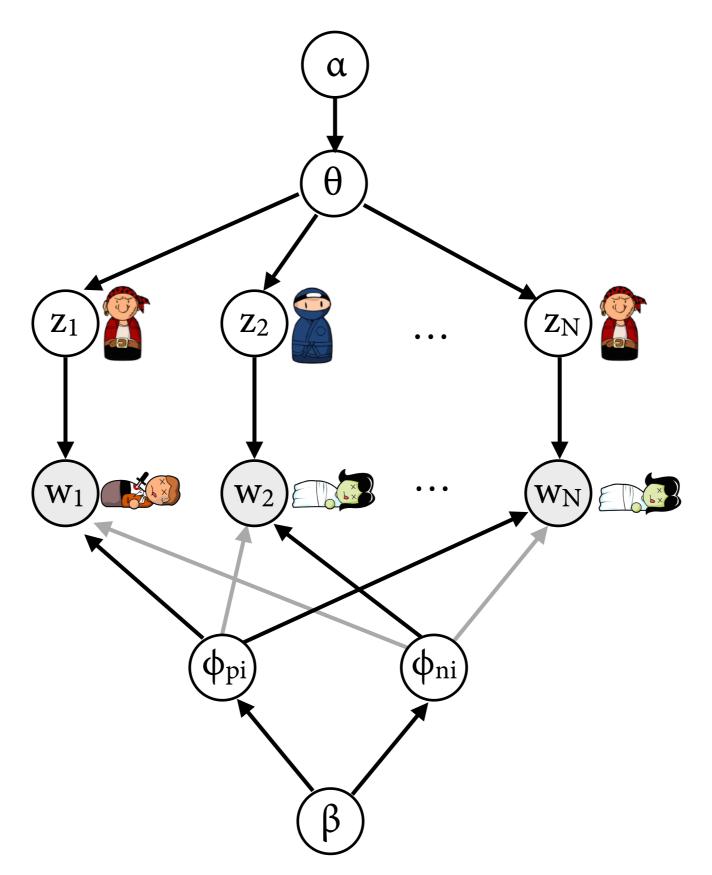
Our task

- We observe N people with their causes of death.
- Questions we are interested in:
 - Who killed each villager? $z_1, ..., z_N \in \{pi, ni\}$
 - How many were killed by pirates, how many by ninjas? $P(pi) = \theta_{pi}$, $P(ni) = \theta_{ni}$; thus, $\theta_{pi} + \theta_{ni} = 1$
 - How likely is it that a pirate chooses to stab someone?
 P(st | pi) = φ_{st|pi}; thus, P(po | pi) = φ_{po|pi} = 1 φ_{st|pi}
 - How likely is it that a ninja chooses to stab someone? $P(st | ni) = \phi_{st|ni}$; thus, $P(po | ni) = \phi_{po|ni} = 1 - \phi_{st|ni}$

Fundamental approach

- Goal: Bayesian model with parameters θ , ϕ_{pi} , ϕ_{ni} .
 - maximum likelihood: try to estimate concrete values for each parameter
 - Bayesian: estimate *probability distribution* $P(\theta, \phi_{pi}, \phi_{ni})$
- In practice, the model will have *latent variables* z, which cannot be observed directly (e.g. pirate/ninja).
- Will marginalize over model parameters and work with P(z | observations) directly.

Generative story: Idea



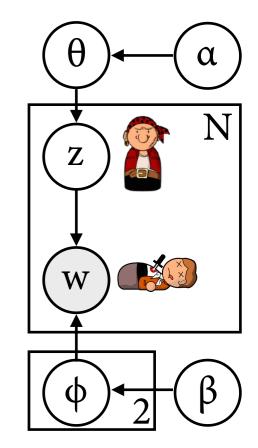
Generative story

• We assume deaths are generated as follows:

 $\begin{aligned} &(\theta_{pi}, \theta_{ni}) \sim \text{Dir}(\alpha, \alpha) \\ &(\phi_{st|pi}, \phi_{po|pi}), (\phi_{st|ni}, \phi_{po|ni}) \sim \text{Dir}(\beta, \beta) \\ &z_1, \dots, z_K \sim \text{Categorical}(\theta) \\ &w_i \sim \text{Categorical}(\phi_{zi}) \end{aligned}$

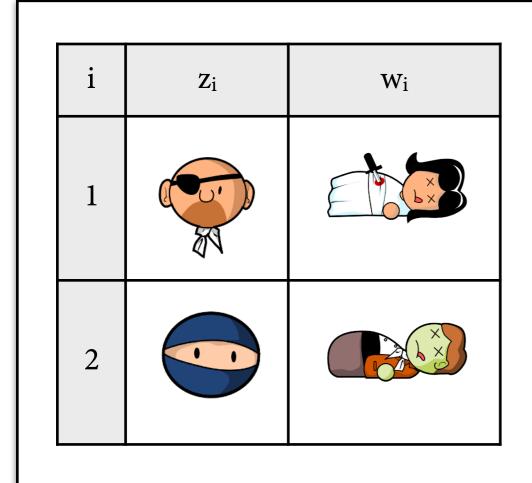
- That is:
 - $P(z_i = pi) = \theta_{pi}$, $P(z_i = ni) = \theta_{ni}$
 - if z_i came out as "pi", then $P(w_i = st) = \phi_{st|pi}$

I abbreviate $\theta = (\theta_{pi}, \theta_{ni}), \phi_{pi} = (\phi_{st|pi}, \phi_{po|pi}), \phi_{ni} = (\phi_{st|ni}, \phi_{po|ni}).$ α, β are assumed given and are called *hyperparameters*.

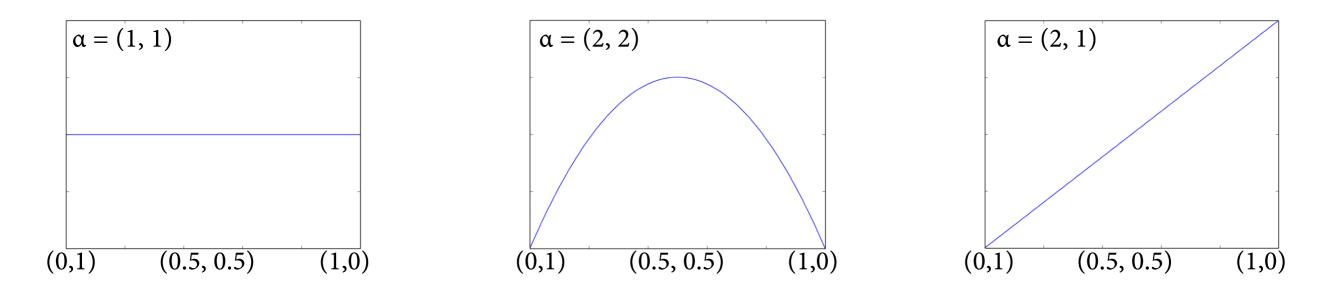


Supervised learning

If all killers are known, $P(M \mid D)$ is easy to compute.



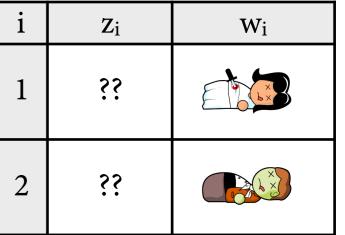
$$\begin{split} P(M) &= \operatorname{Dir}_{\alpha,\alpha}(\theta) \cdot \operatorname{Dir}_{\beta,\beta}(\phi_{\mathrm{pi}}) \cdot \operatorname{Dir}_{\beta,\beta}(\phi_{\mathrm{ni}}) \\ &\propto \theta_{\mathrm{pi}}^{\alpha-1} \cdot \theta_{\mathrm{ni}}^{\alpha-1} \cdot \phi_{\mathrm{st}|\mathrm{pi}}^{\beta-1} \cdot \phi_{\mathrm{po}|\mathrm{pi}}^{\beta-1} \cdot \phi_{\mathrm{st}|\mathrm{ni}}^{\beta-1} \cdot \phi_{\mathrm{po}|\mathrm{ni}}^{\beta-1} \\ P(D \mid M) &= P(z_1 = \mathrm{pi}, w_1 = \mathrm{st}, z_2 = \mathrm{ni}, w_2 = \mathrm{po}) \\ &= \theta_{\mathrm{pi}} \cdot \phi_{\mathrm{st}|\mathrm{pi}} \cdot \theta_{\mathrm{ni}} \cdot \phi_{\mathrm{po}|\mathrm{ni}} \\ P(M \mid D) \propto P(D \mid M) \cdot P(M) \\ &\propto \theta_{\mathrm{pi}}^{\alpha} \cdot \theta_{\mathrm{ni}}^{\alpha} \cdot \phi_{\mathrm{st}|\mathrm{pi}}^{\beta-1} \cdot \phi_{\mathrm{po}|\mathrm{pi}}^{\beta-1} \cdot \phi_{\mathrm{po}|\mathrm{ni}}^{\beta-1} \\ &\propto \operatorname{Dir}_{\alpha+1,\alpha+1}(\theta) \cdot \operatorname{Dir}_{\beta+1,\beta}(\phi_{\mathrm{pi}}) \cdot \operatorname{Dir}_{\beta,\beta+1}(\phi_{\mathrm{ni}}) \end{split}$$



Unsupervised learning

In the original scenario, we can only observe deaths, not killers. Then P(D | M) i
 is less convenient: 1

 $P(D \mid M) = P(w_1 = \text{st}, w_2 = \text{po} \mid M)$ = $\sum_{k_1, k_2 \in \{\text{pi}, \text{ni}\}} P(z_1 = k_1, w_1 = \text{st}, z_2 = k_2, w_2 = \text{po} \mid M)$



• This sums over a number of terms that is exponential in N, and thus infeasible to compute.

•
$$M = (\theta, \phi_{pi}, \phi_{ni})$$

Latent variables

• Many interesting quantities can be expressed in terms of expected values over the latent variables.

$$P(z \mid w) = \int P(z, M \mid w) \, \mathrm{d}M = \int P(z \mid M, w) \cdot P(M \mid w) \, \mathrm{d}M$$

• Some examples:

ninja/pirate mixing proportion $\frac{1}{N} \cdot E_{P(z|w)}[C(z_i = \text{ninja})]$

pirate habits

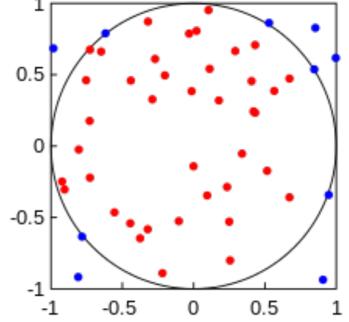
$$E_{P(z|w)}[C(z_i = \text{pirate}, w_i = \text{stab})] / E_{P(z|w)}[C(z_i = \text{pirate})]$$

probability that first villager was killed by a pirate $E_{P(z|w)}[||z_1 = \text{pirate}||]$

Estimating expected values

- Expected values can be approximated by *sampling*.
 To compute E_{P(X)}[f(X)]:
 - draw S samples $x^{(1)}$, ..., $x^{(S)}$ from P(X)
 - estimate $E[f(X)] \approx \frac{1}{S} \cdot \sum_{i=1}^{S} f(x^{(i)})$
- Example: To estimate π , sample points from square and count how many fall into the circle.

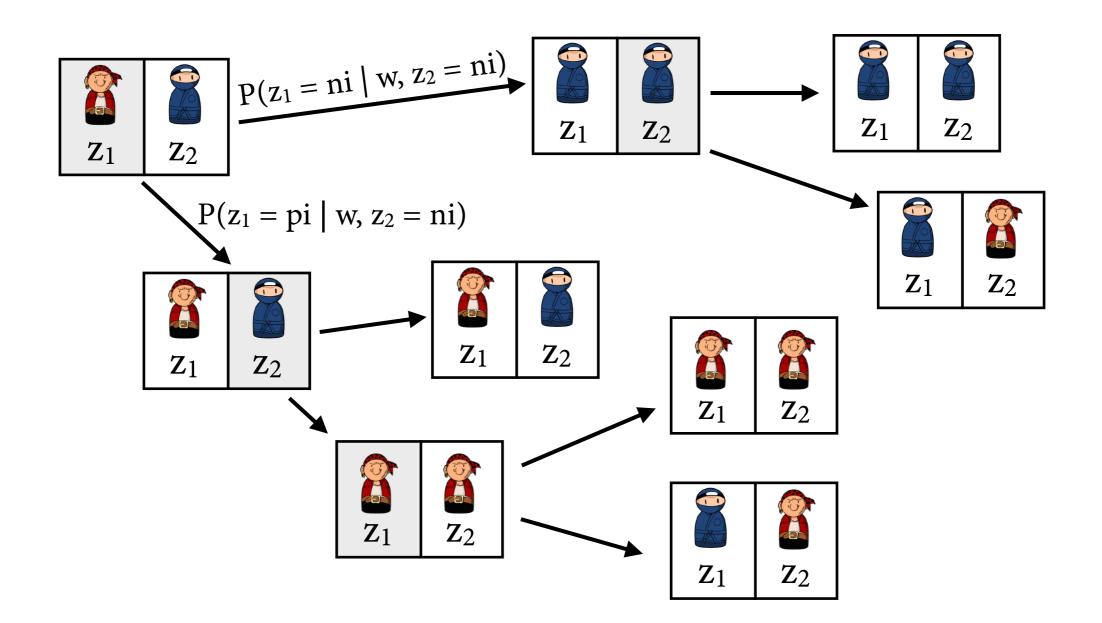
 $\pi/4 \approx E_{P(x,y)} [\|x^2 + y^2 \le 1\|]$



EVs under latent variables

- We could estimate expected values under P(z | w) using sampling. However, P(z | w) is usually of a form that makes direct sampling difficult.
- Instead, we can use *Gibbs sampling*:
 - Start from an initial guess $z_1, ..., z_N$ for the latent variables.
 - Repeatedly resample guess for some z_i conditioned on all other z's, i.e. from P(z_i | w, z_{-i}). This is much easier than sampling from P(z | w) itself.
 - Can prove that probability of observing a sample for z as a whole converges to P(z | w).

Gibbs Sampling



Transition probabilities

- It remains to determine the transition probabilities
 P(z_i | w, z_{-i}).
- Formula turns out to be remarkably simple:

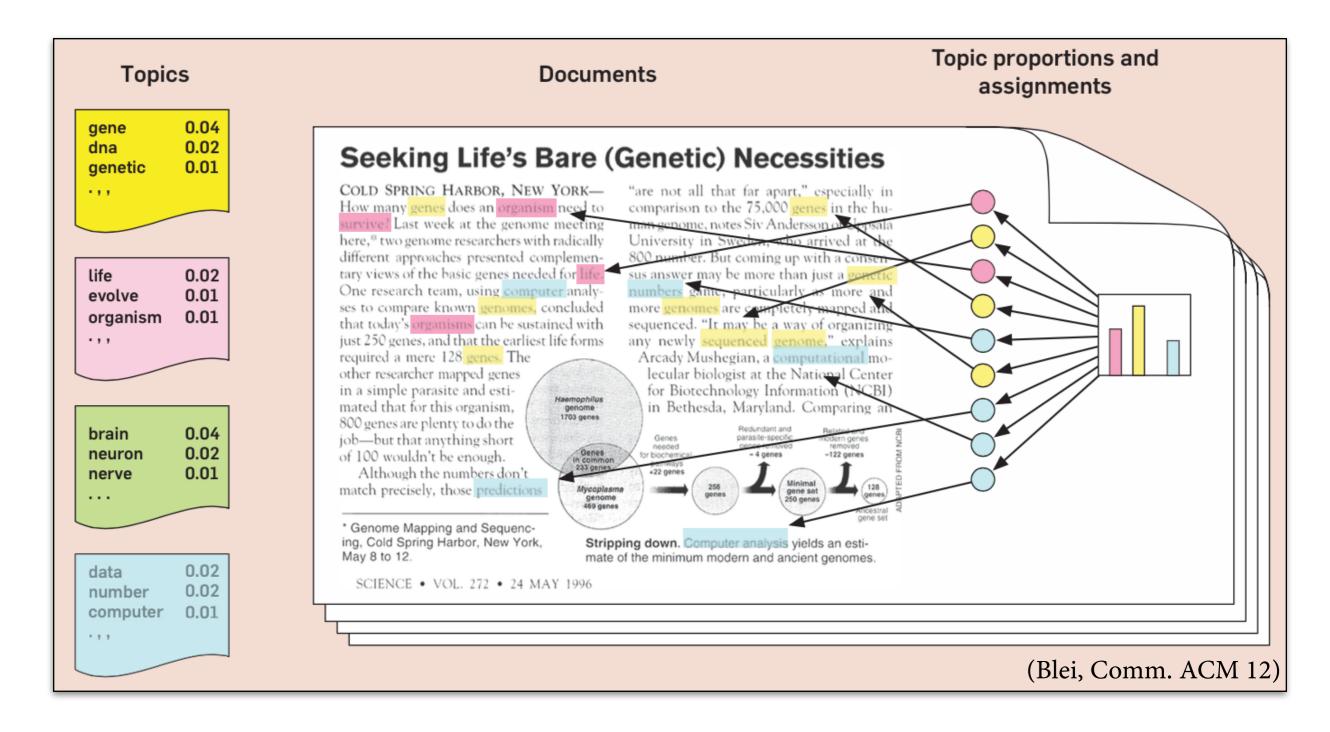
$$P(z_{i} = pi \mid w, z_{-i}) \propto P(w, z_{-i}, z_{i} = pi)$$

$$= \int \int P(w, z_{-i}, z_{i} = pi, \theta, \phi) d\theta d\phi$$

$$= \dots$$

$$\propto (n_{pi}^{(-i)} + \alpha_{pi}) \frac{n_{pi,w_{i}}^{(-i)} + \beta_{w_{i}|pi}}{\sum_{w'} n_{pi,w'}^{(-i)} + \beta_{w'}|pi}$$
people other than i that
were killed by pirates
in current sample
people other than i that
were killed by pirates
wing method w'

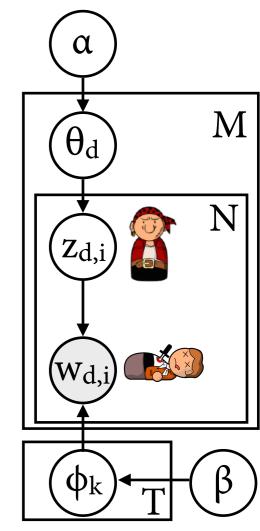
Topic models



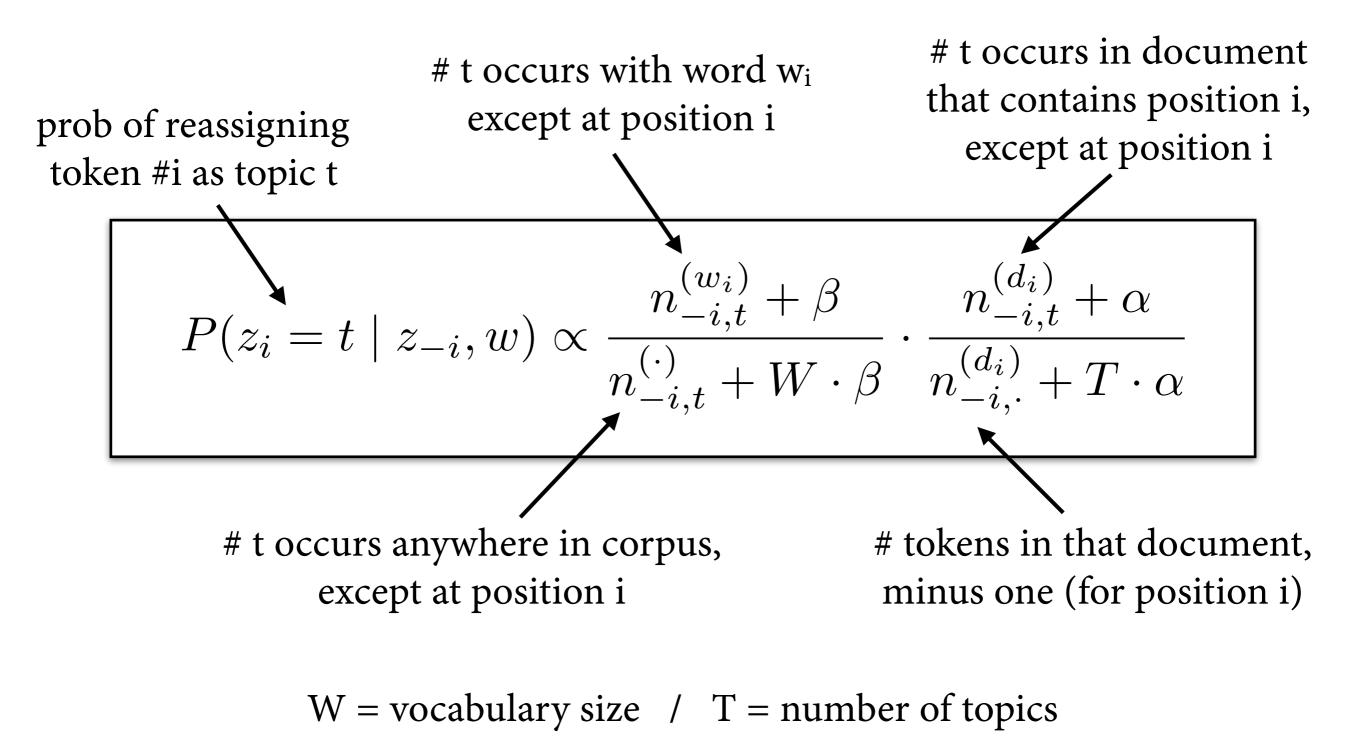
learn: word probs. ← given: raw documents → learn: topic mixture for (abstract) *topics* in each document

Latent Dirichlet Allocation

- Topic modeling is almost the same problem as the pirate/ninja problem:
 - abstract topics = {pirate, ninja}
 - words in document = {stabbed, poisoned}
- Full LDA makes two changes:
 - can have T topics instead of just two, and also more than two different words
 - there are M > 1 *documents*, and each document
 can have its own mixture θ_d of topics

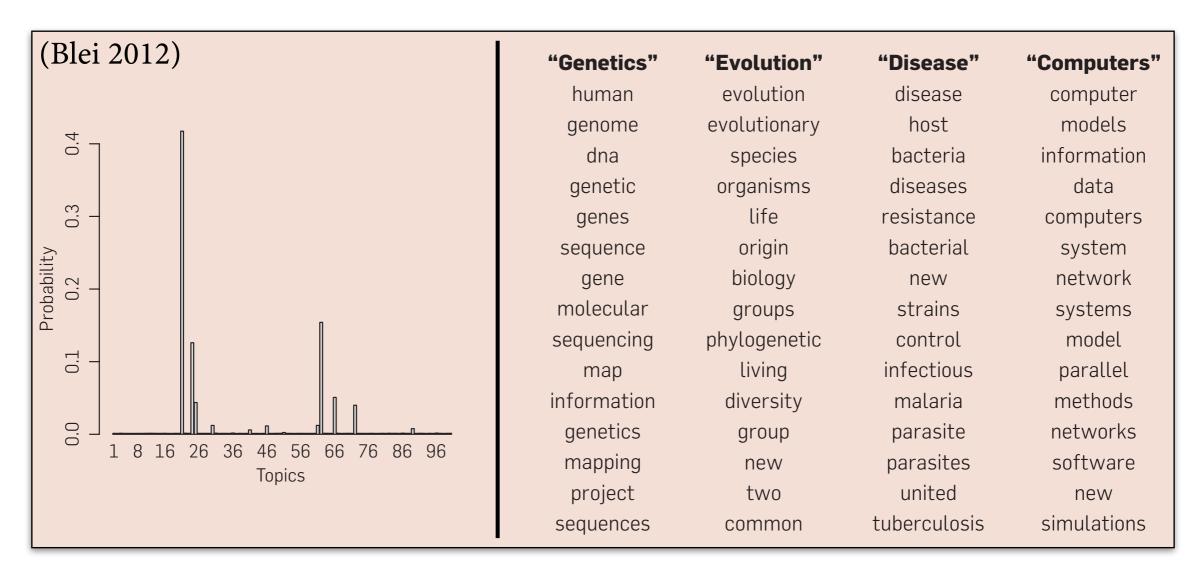


Gibbs sampler for LDA



(Griffiths & Steyvers 2004)

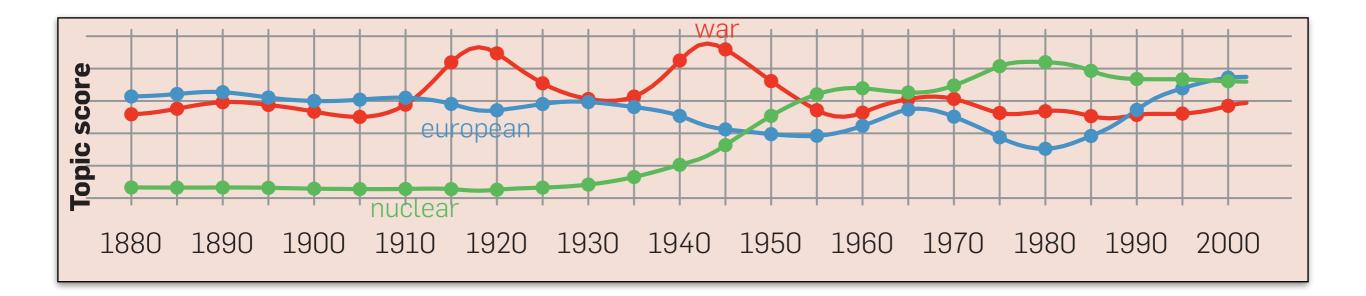
Examples



topic mixture for one article in *Science* $\begin{array}{l} 15 \text{ words with highest } \varphi_{k,w} \\ \text{for each topic over whole corpus} \\ \text{(with made-up topic label)} \end{array}$

Examples

development of topics from Science over time (1880-2002)



Conclusion

- LDA and extensions for topic modeling.
 - Topics interesting in their own right, also useful in various applications.
 - Simplest useful Bayesian model in NLP.
- We used (collapsed) Gibbs sampling to approximate expected values.
 - Alternative is *Variational Bayes:* approximate P(M|D) on paper, then solve integral exactly.
- Limitation: Number T of topics must be given. We will fix this next time.